



F1/10 YELLOWTAILS

Autonomous Racing
For Everyone

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Faculty Mentor: Isaac Shaffer

Introduction

Clients



Dr. Nghiem

- Assistant Professor
- Director of ICONS Lab



Doan Nguyen

- Graduate Research Assistant

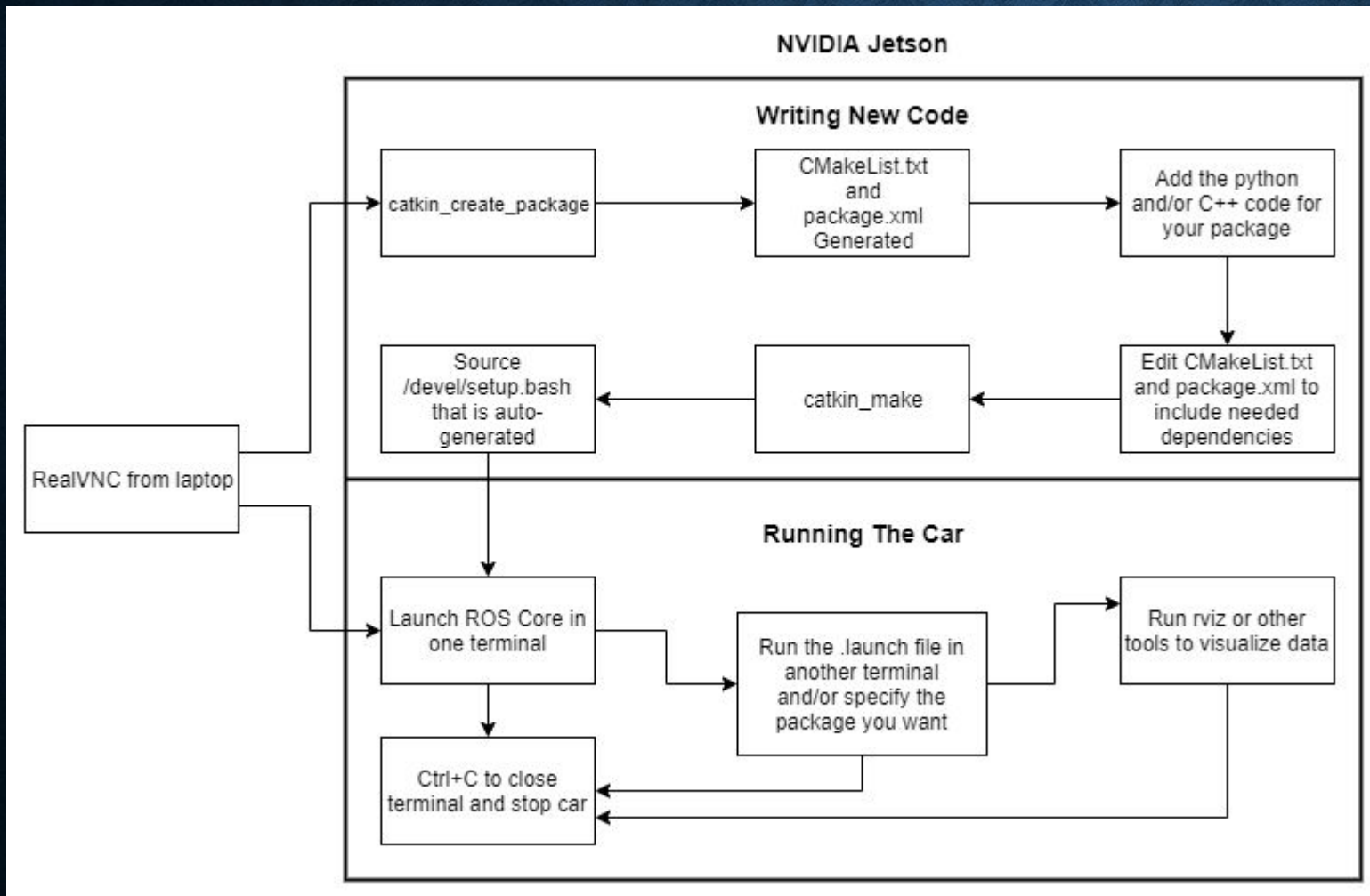
Flagstaff's F1/10 Robo-Racing Project



Director and researcher of the Intelligent Control Systems (ICONS) Laboratory

Robotic Operating System (ROS)

Problem Statement



1. Overly complicated

2. Disconnected Configurations

3. No emergency stop

Solutions Overview

An Interactable System
For High School Students!

1. Implicit File
Organization

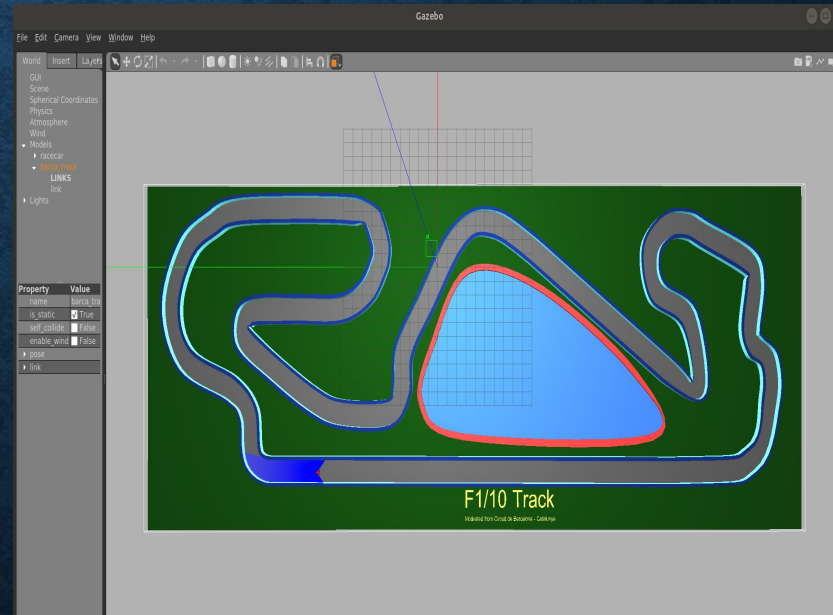


2. Configuration
Window

3. Kill Switch
System

Requirements Acquisition

- Weekly meeting with clients in ICONS lab
- ROS Research outside ICONS Lab
- Sourcing UPenn F1/10 simulation



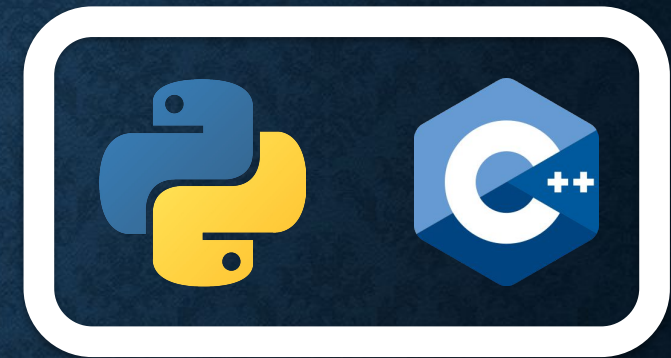
Environmental Software Requirements



- Driver System



- Ambient System



- Languages used to create ROS Nodes

Environmental Hardware Requirements

NVIDIA Jetson



- Brains of the car

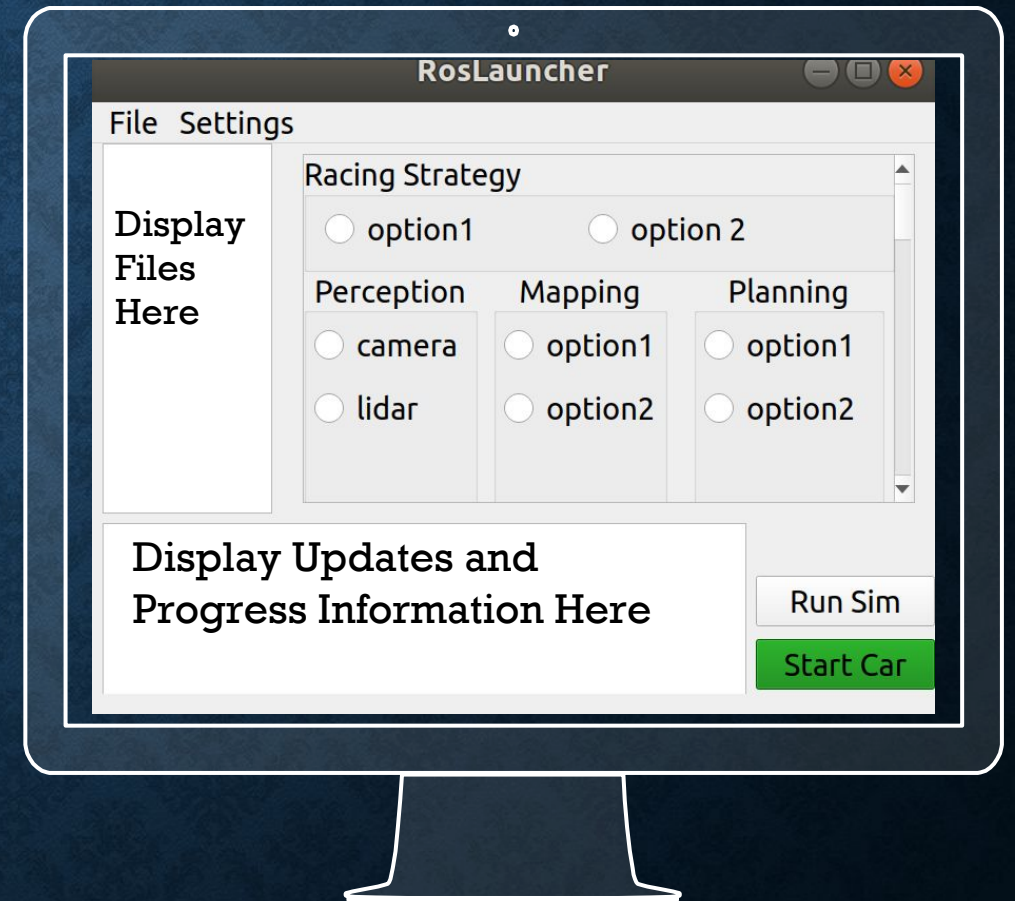
Raspberry PI



- Students Computer

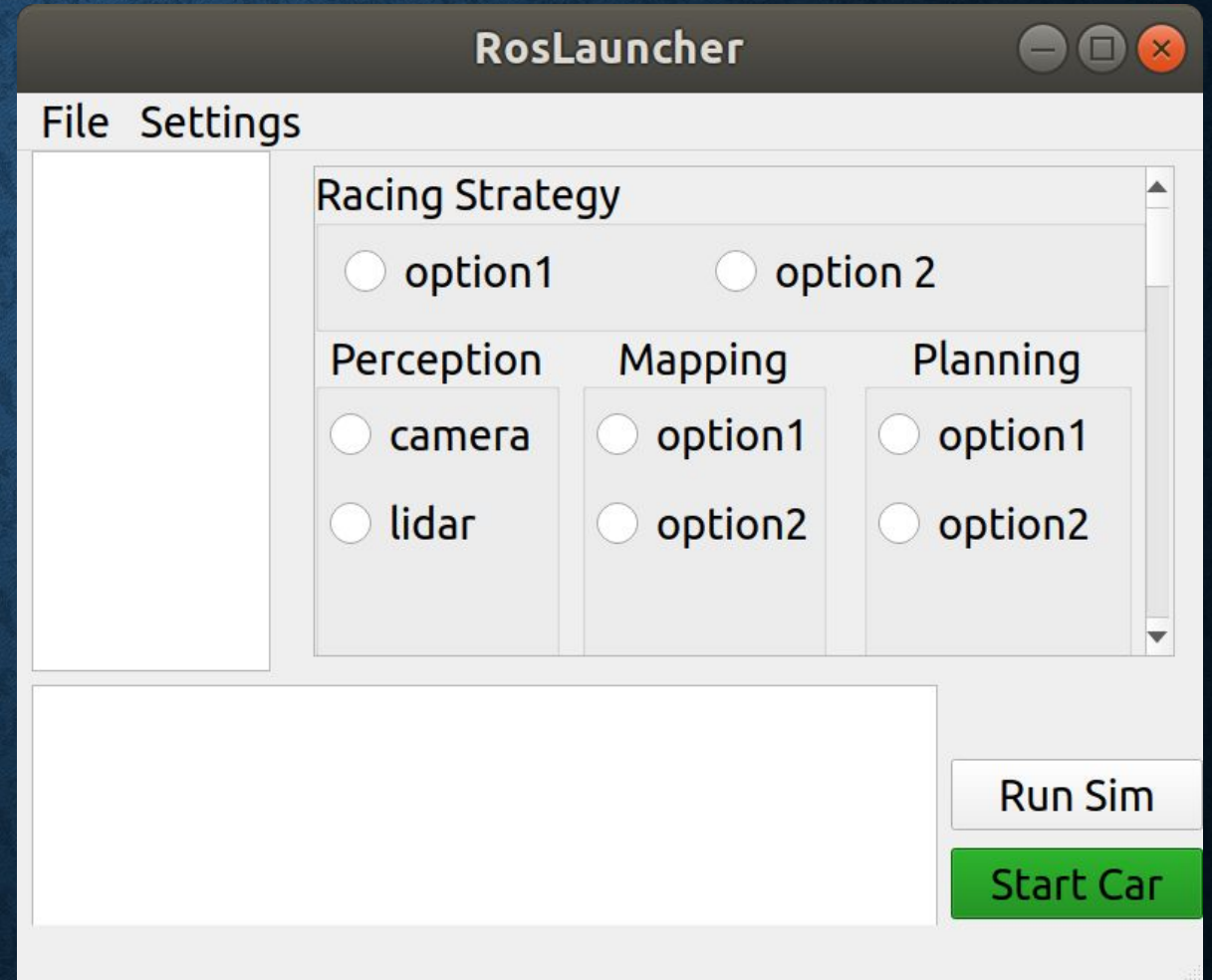
Functional Requirements

- Configuration System
- Communication Tool Kit
- Implicit File Organization
- Profiler
- Console



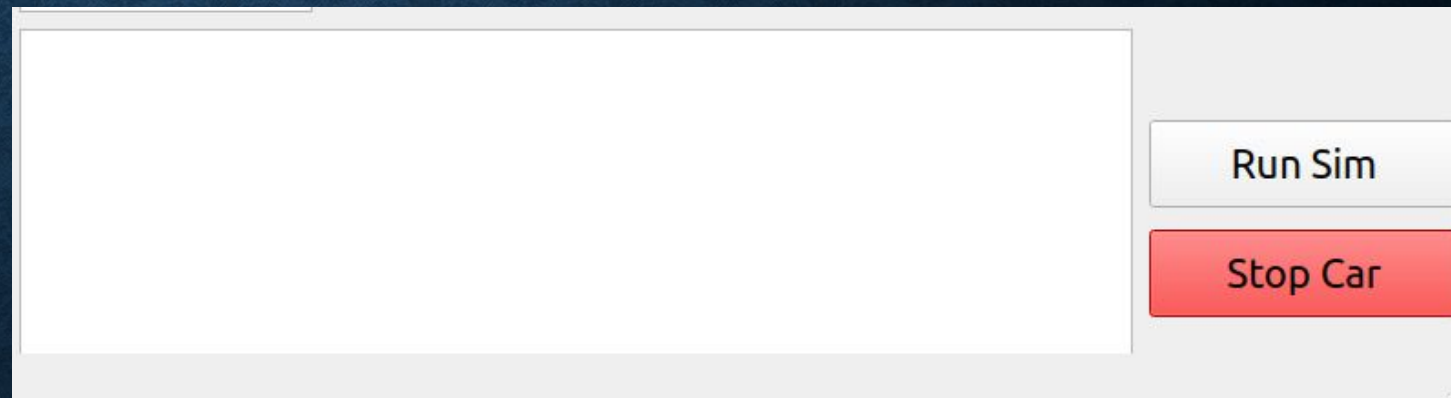
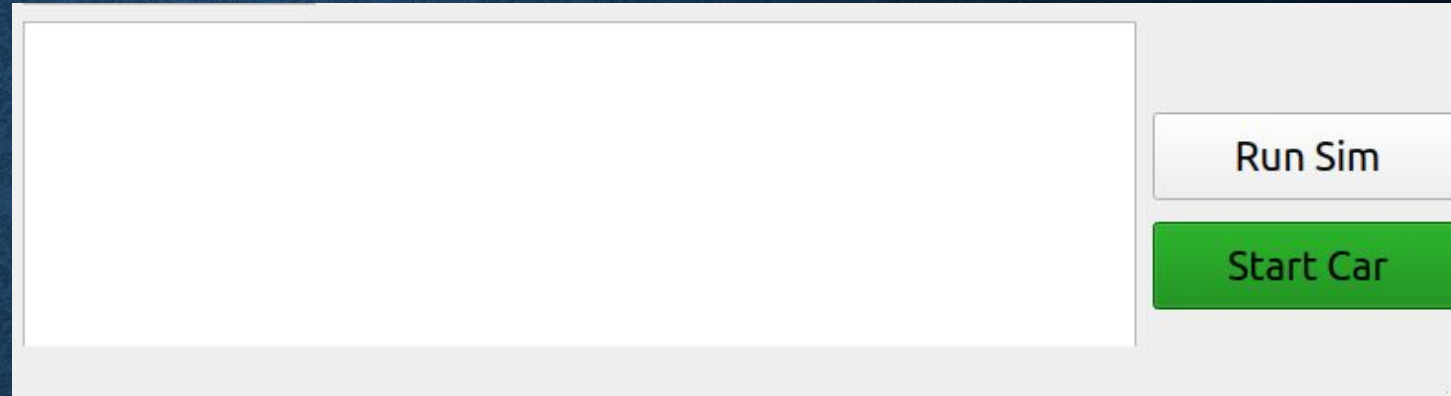
Configuration System

- No code required
- No misconfiguration
- Upload of around 5 seconds



Kill Switch System

- Ability to Start and Stop Car via Button
- Listener Script for checking connection
- If connection is lost, Listener Script Stops Vehicle



Risks and Feasibility



Losing connection

Internet interruption ->
wifi-SSH connection lost.

Severity: High

Likelihood: High

Responses: Onboard script to
check connection

Operational error

Actual operating error ->
Car deviates from the
ordered track

Severity: Medium/High

Likelihood: High

Responses: Run simulation to
minimize the error

Compatibility

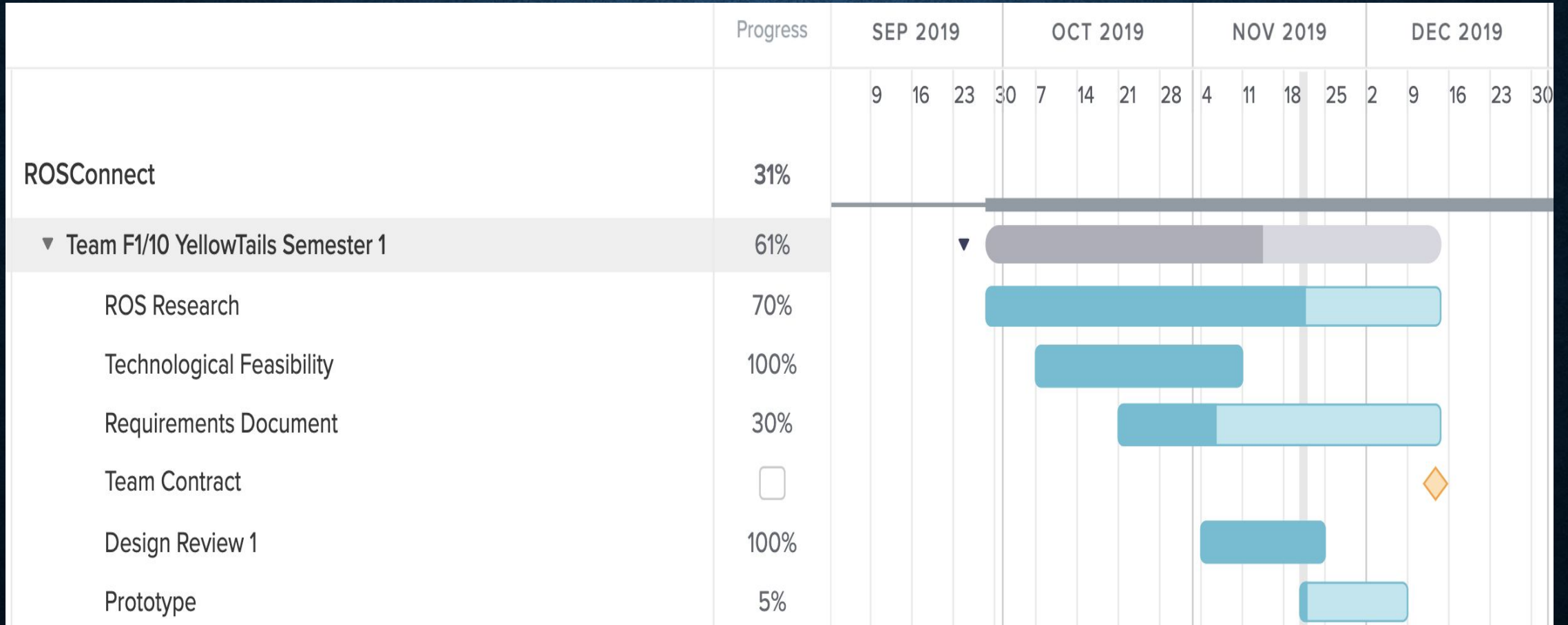
GUI, Raspberry Pi, Ubuntu
compatibility

Severity: High

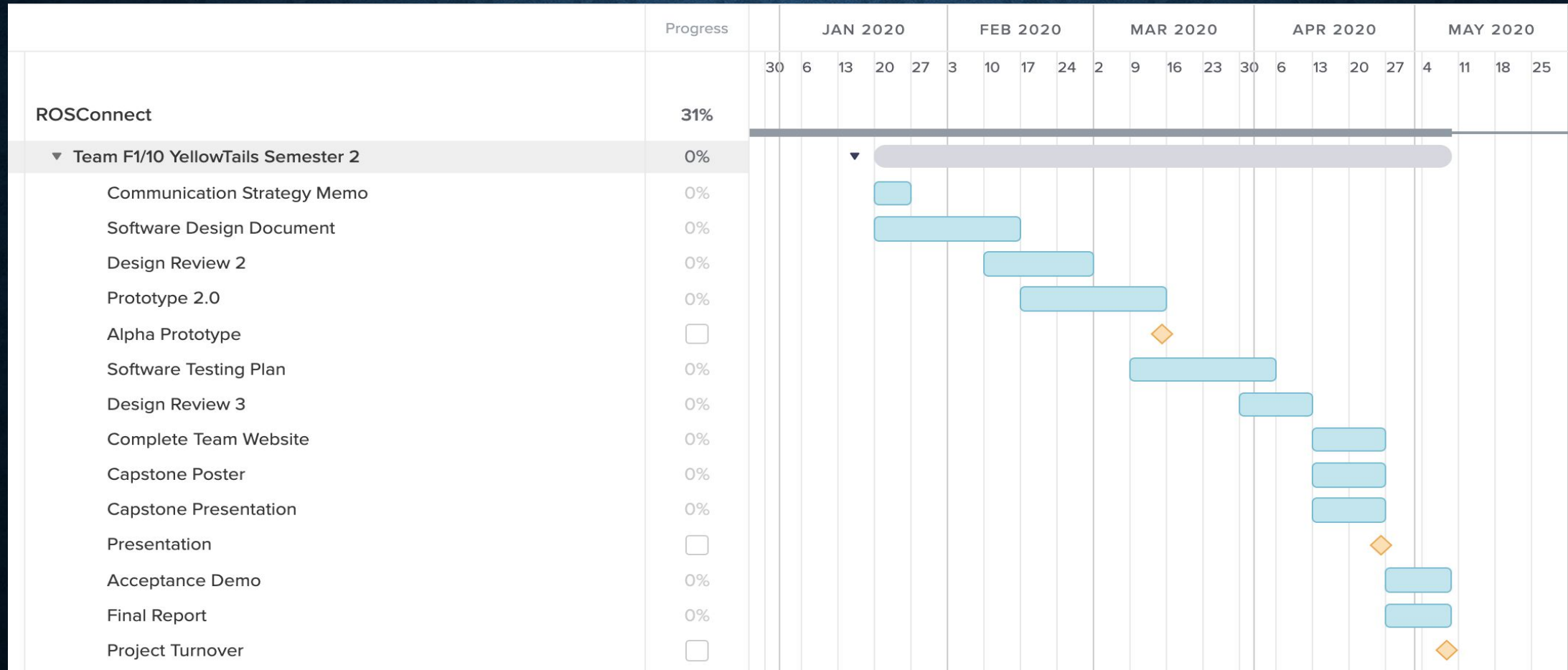
Likelihood: Low

Responses: Test whether
they can work together or not

Schedule



Schedule (Spring Semester)



Conclusion

Big Picture

- Self-driving cars are the future!



Problem

- Autonomous F1/10 program is currently Inaccessible to HS students



Solution

- Graphical User Interface for Better Accessibility

